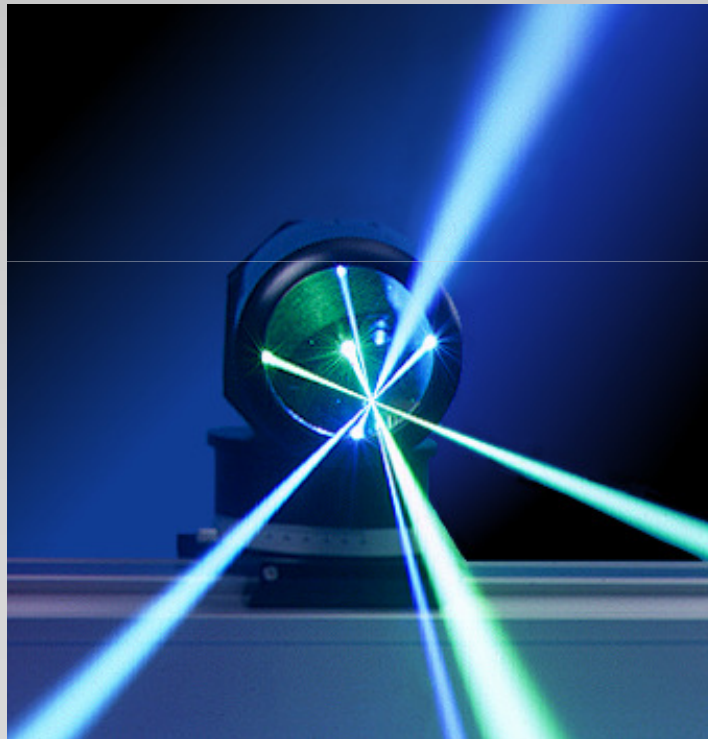


Laser Doppler Anemometry

Introduction to principles and applications



Characteristics of LDA

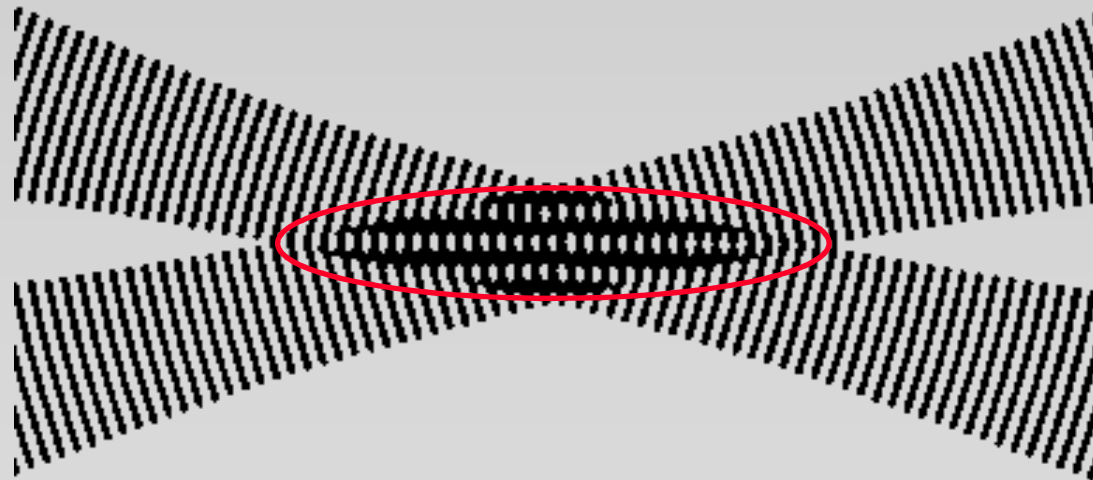
- Invented by Yeh and Cummins in 1964
- Velocity measurements in Fluid Dynamics (gas, liquid)
- Up to 3 velocity components
- Non-intrusive measurements (optical technique)
- Absolute measurement technique (no calibration required)
- Very high accuracy
- Very high spatial resolution due to small measurement volume
- Tracer particles are required

Applications of LDA

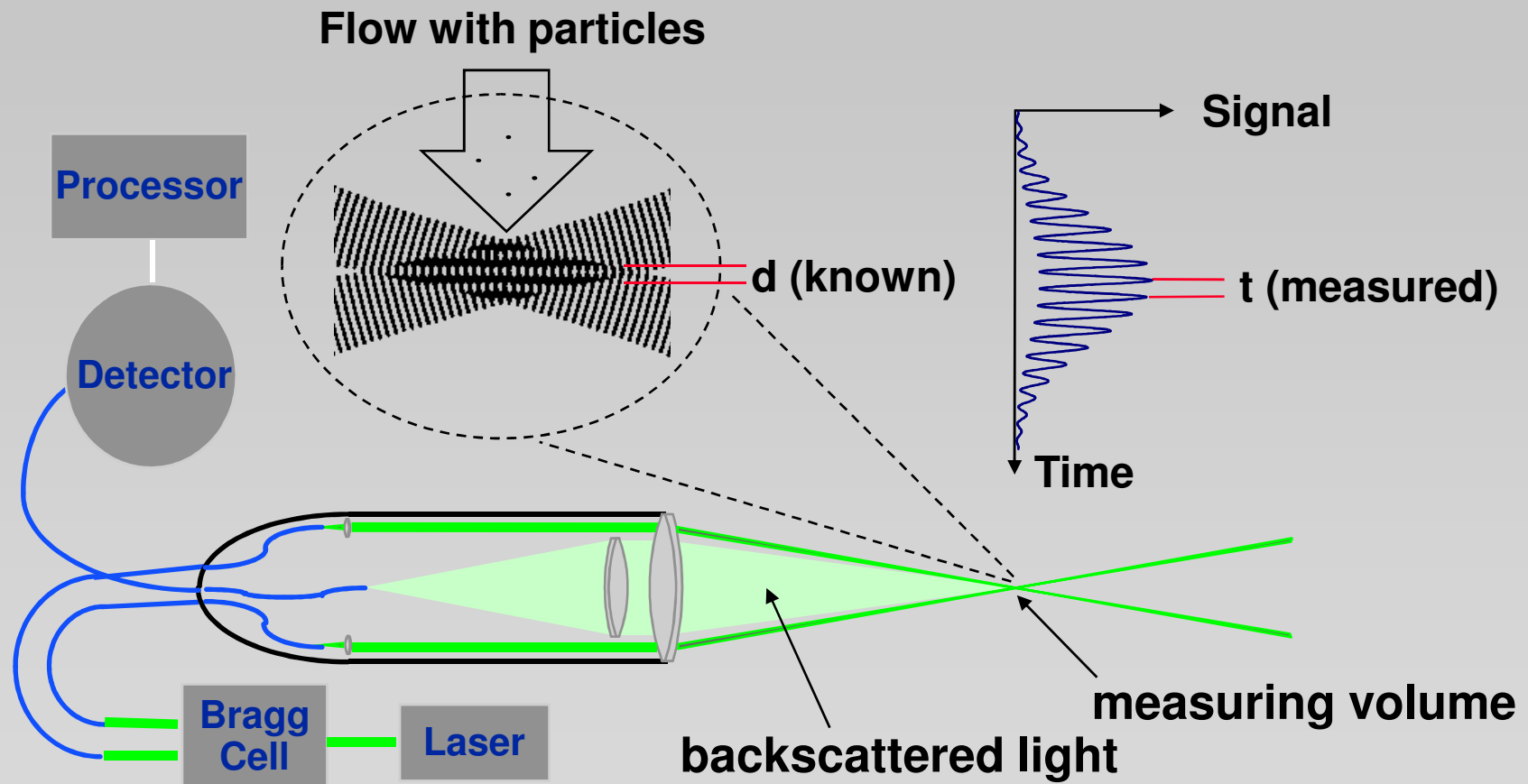
- Laminar and turbulent flows
- Investigations on aerodynamics
- Supersonic flows
- Turbines, automotive etc.
- Liquid flows
- Surface velocity and vibration measurement
- Hot environments (Flames, Plasma etc.)
- Velocity of particles
- etc, etc, etc.

LDA - Fringe Model

- Focused Laser beams intersect and form the measurement volume
- Plane wave fronts: beam waist in the plane of intersection
- Interference in the plane of intersection
- Pattern of bright and dark stripes/planes



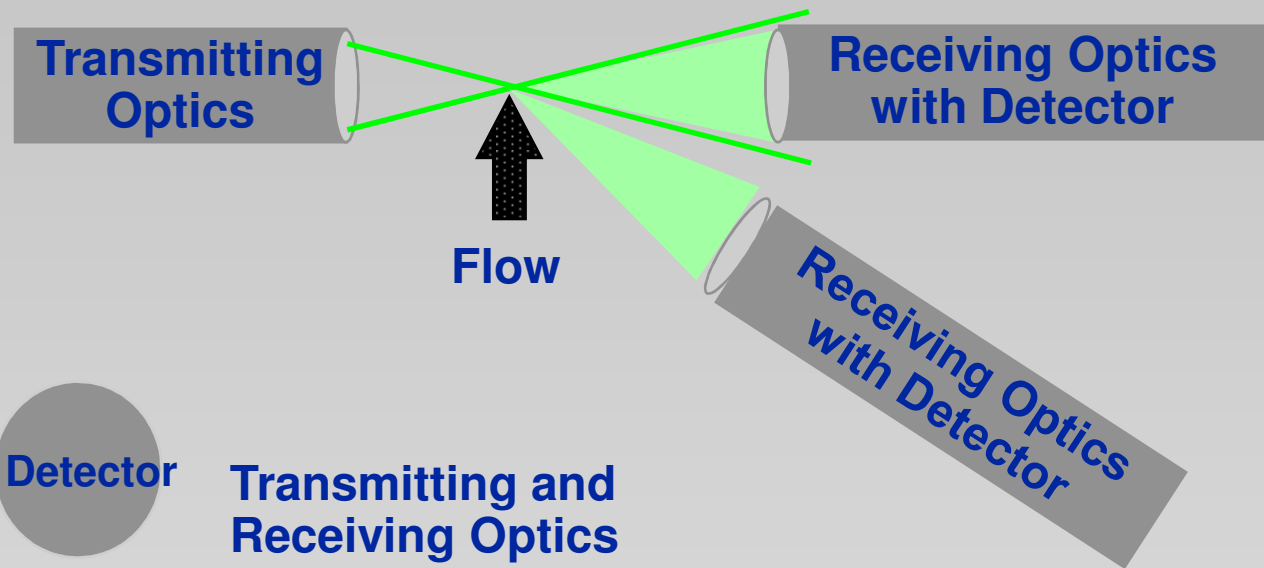
Velocity = distance/time



System Configurations

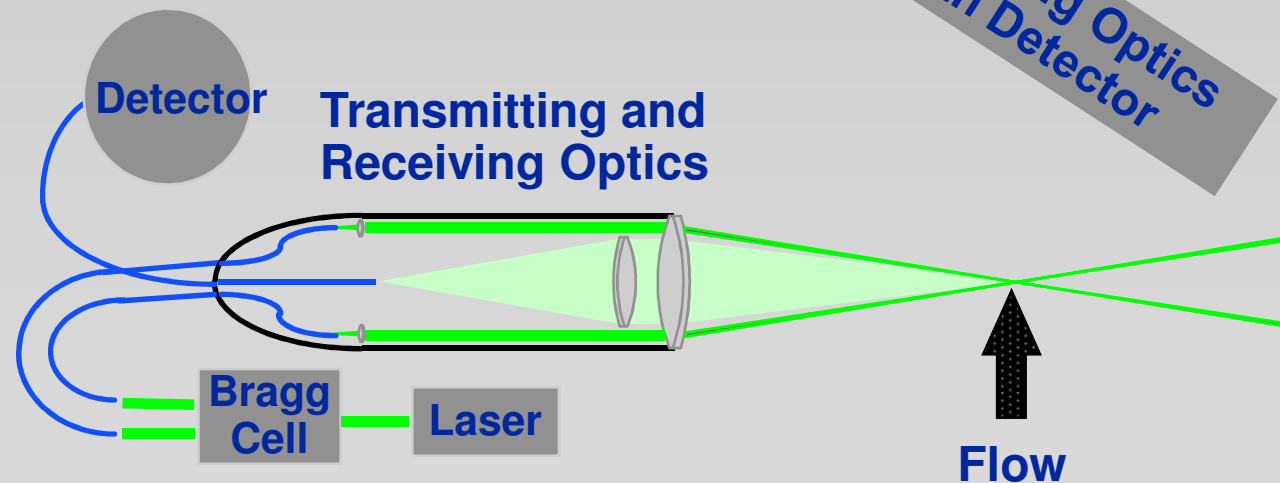
Forward scatter
and side scatter
(off-axis)

- Difficult to align,
- vibration sensitive

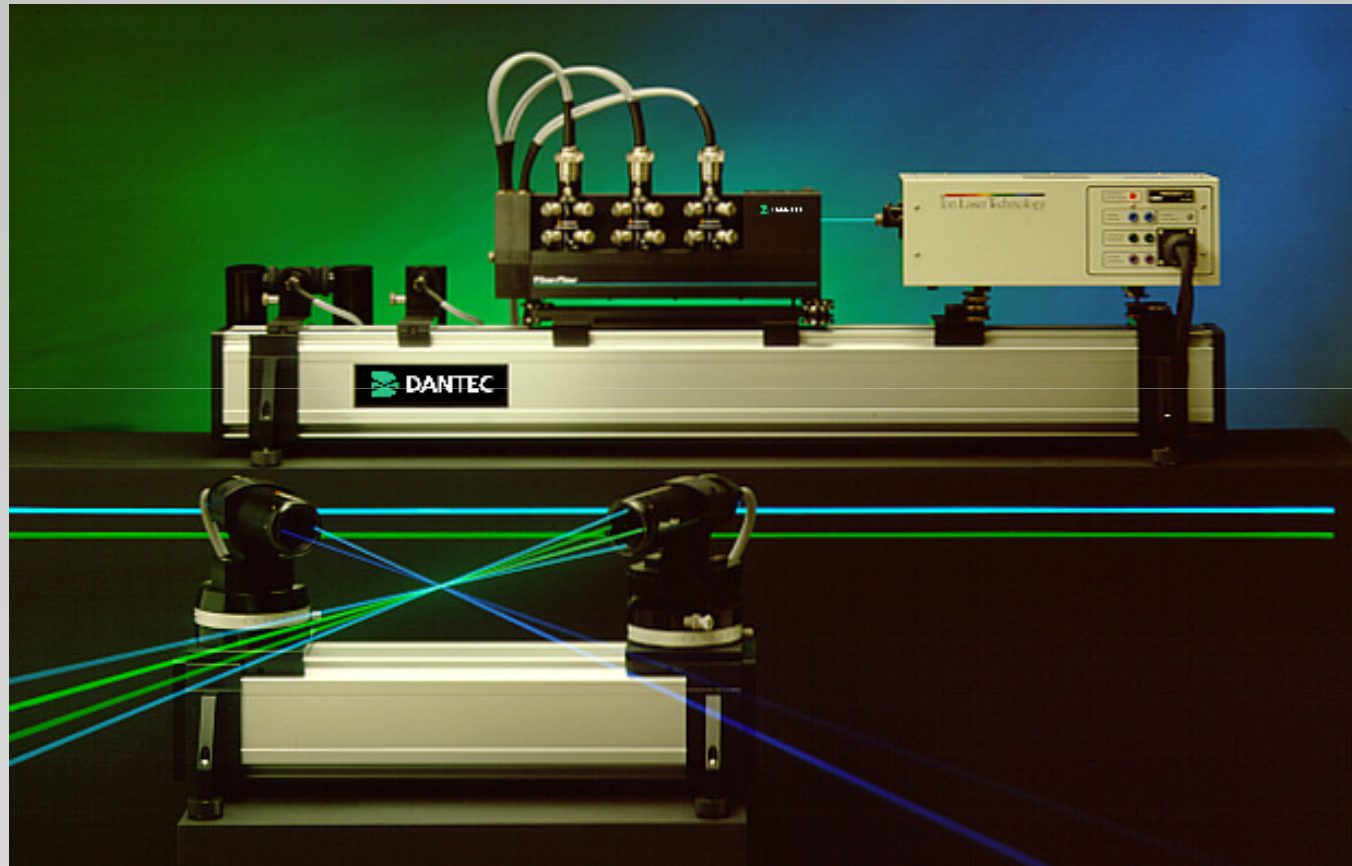


Backscatter

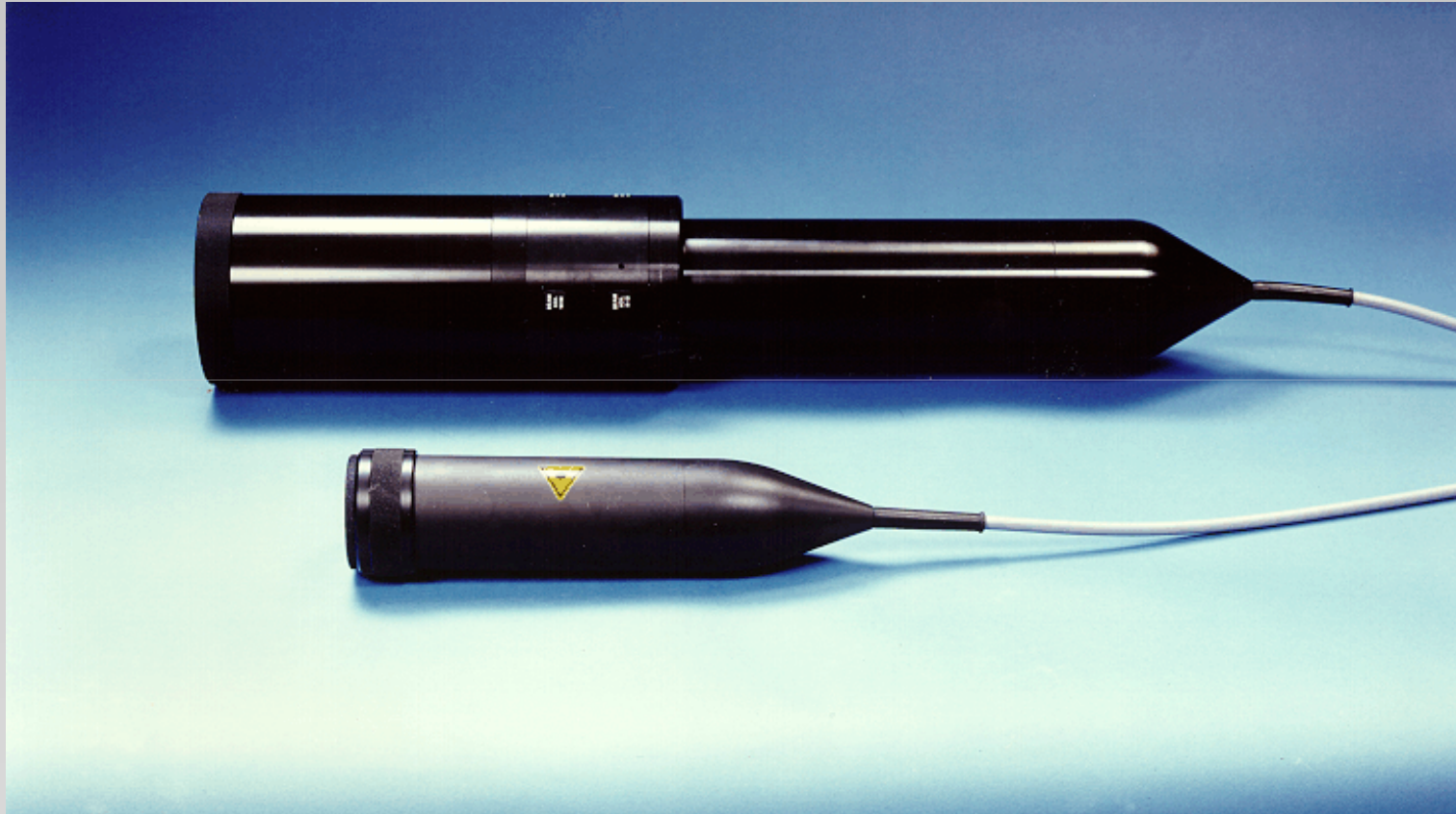
- Easy to align
- User friendly



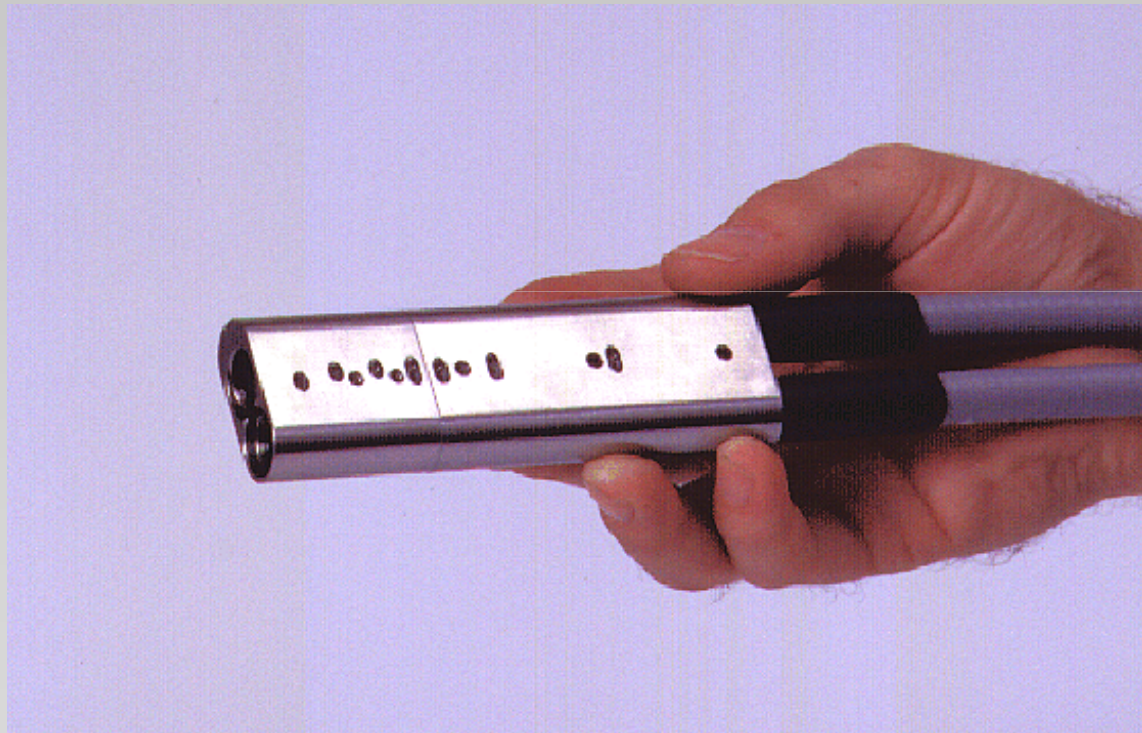
LDA Fibre Optical System



60 mm and 85 mm *FiberFlow* probes



The small integrated 3D *FiberFlow* probe



Measurement of air flow around a helicopter rotor model in a wind tunnel

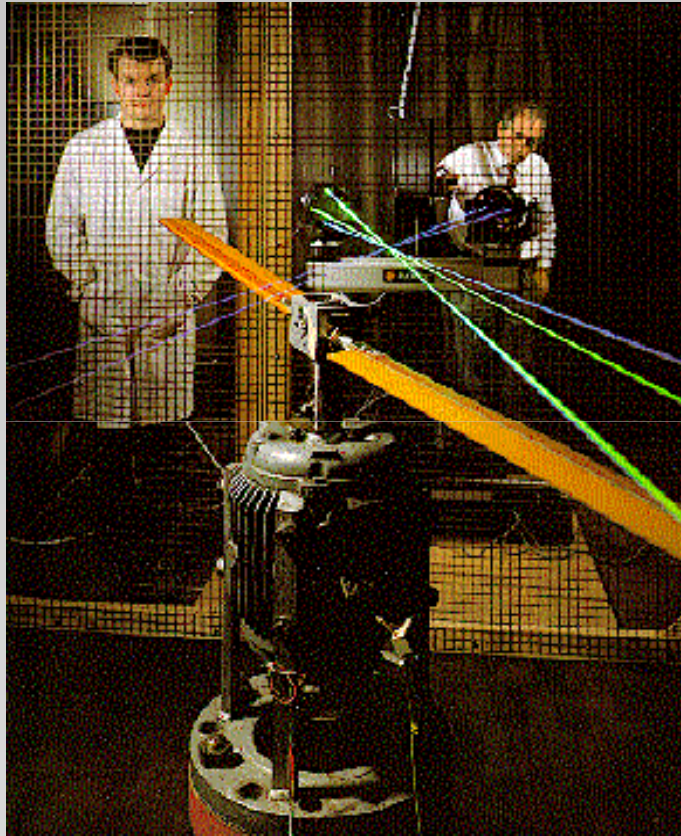


Photo courtesy of University of Bristol, UK

Measurement of water flow inside a pump model

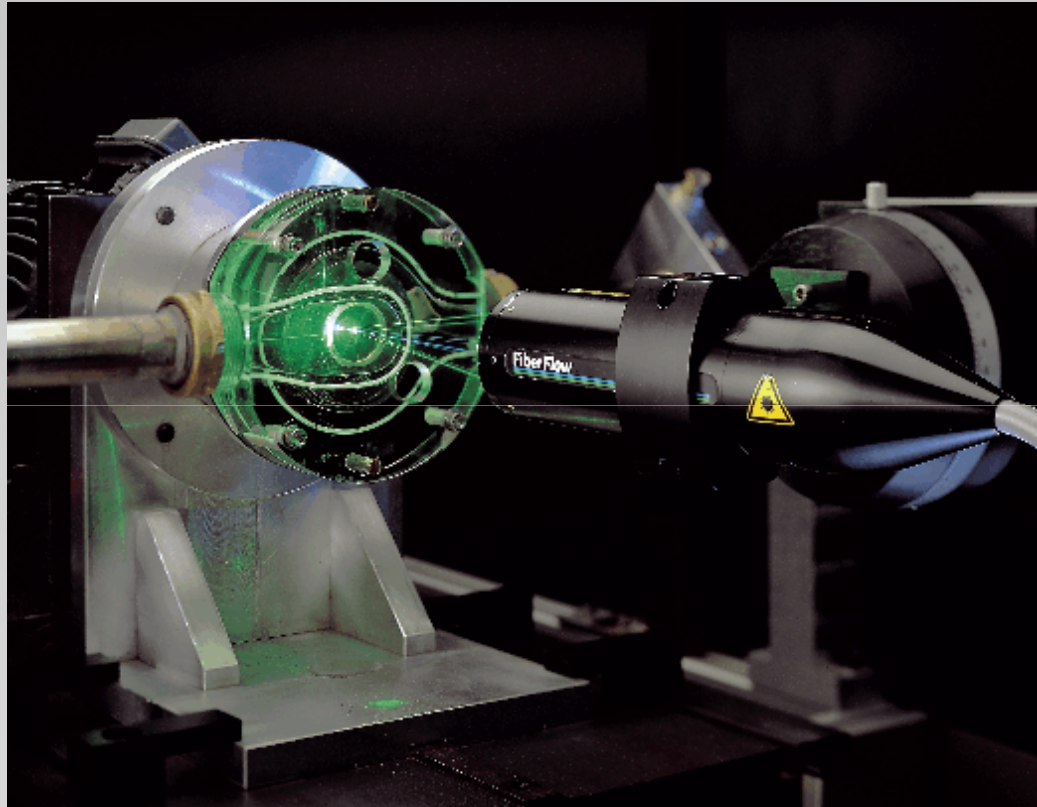
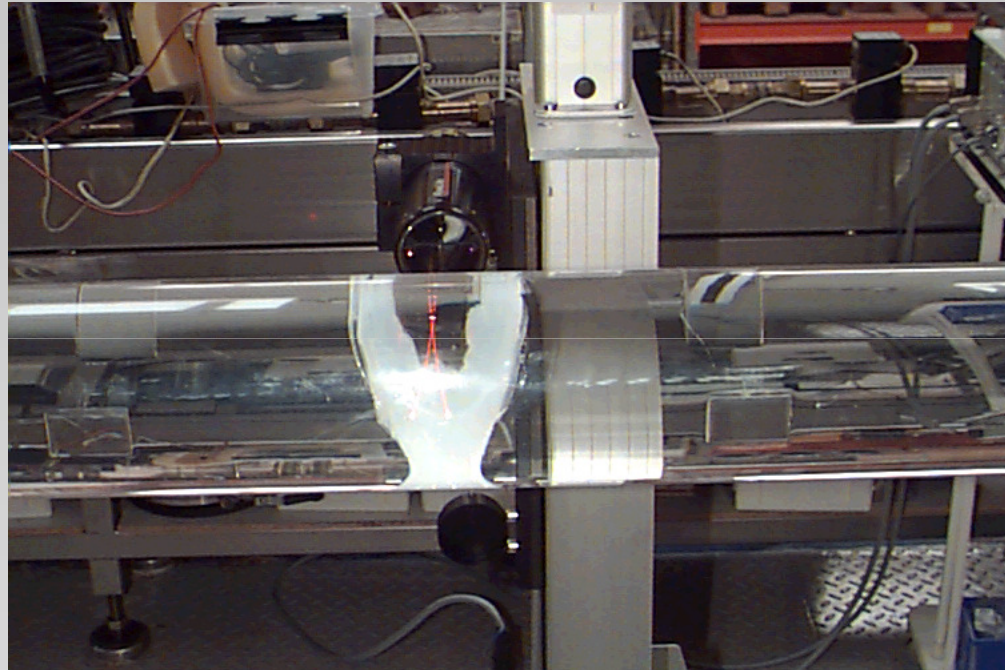
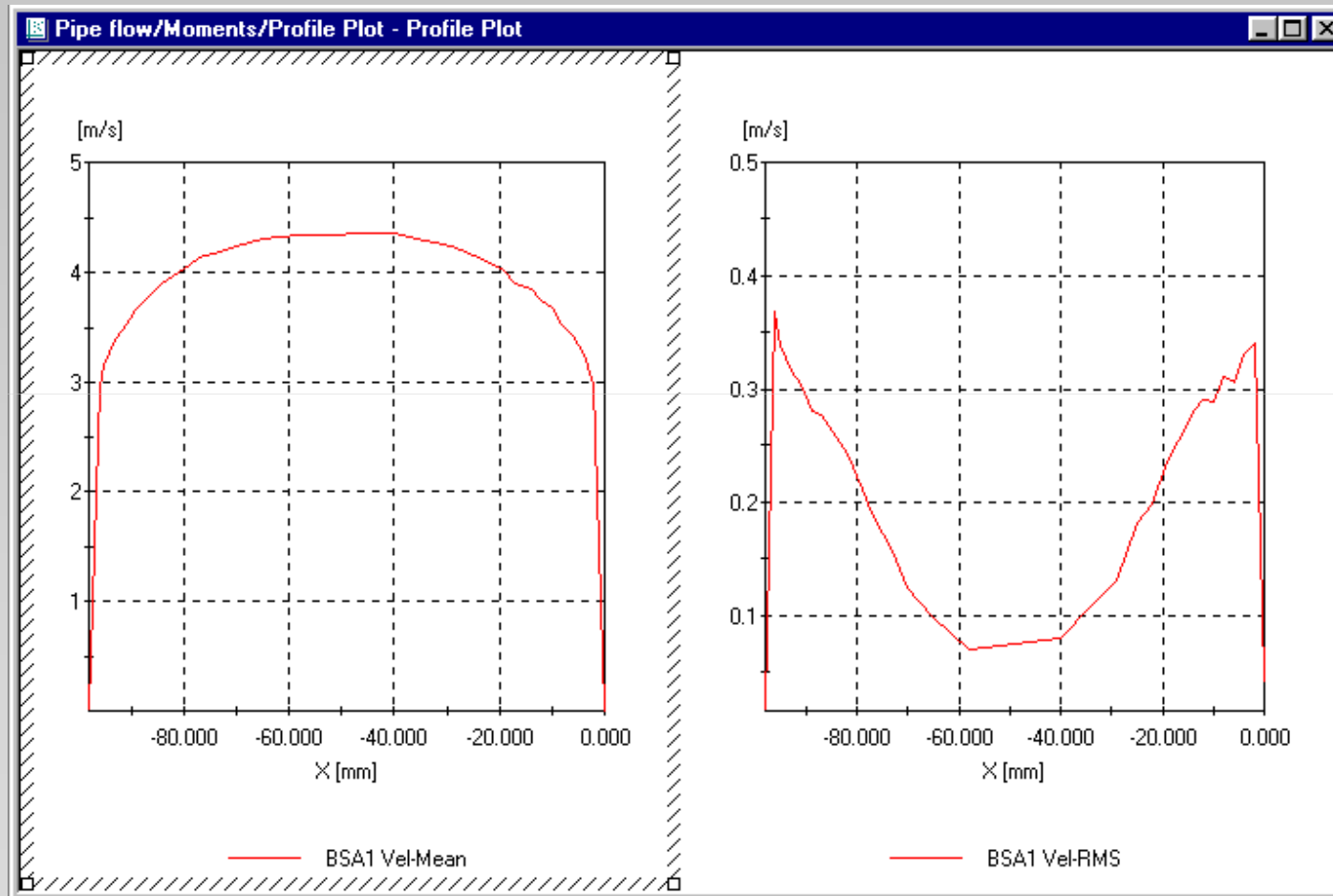


Photo courtesy of Grundfos A/S, DK

Measurement of velocity profiles in a water pipe



Velocity profile, fully developed turbulent pipe flow



Measurement of flow field around a 1:5 scale car model in a wind tunnel

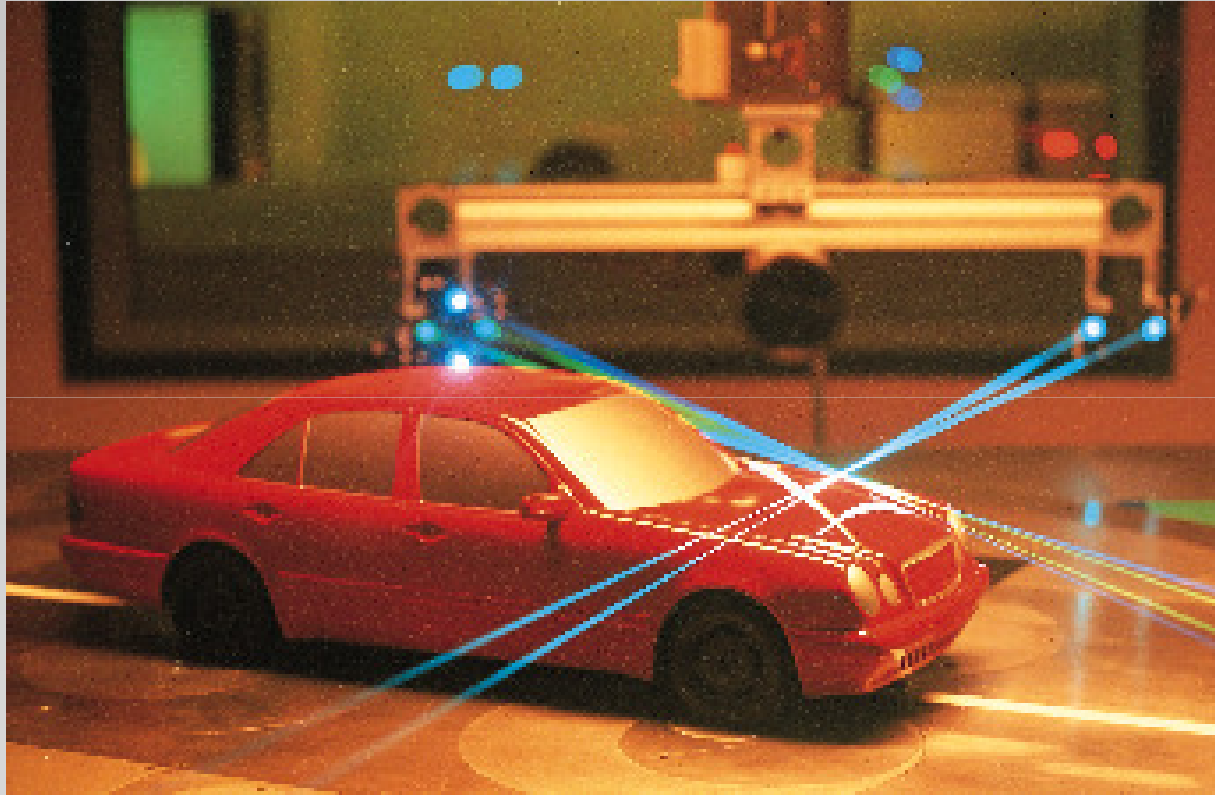


Photo courtesy of Mercedes-Benz, Germany

Measurement of wake flow around a ship model in a towing tank

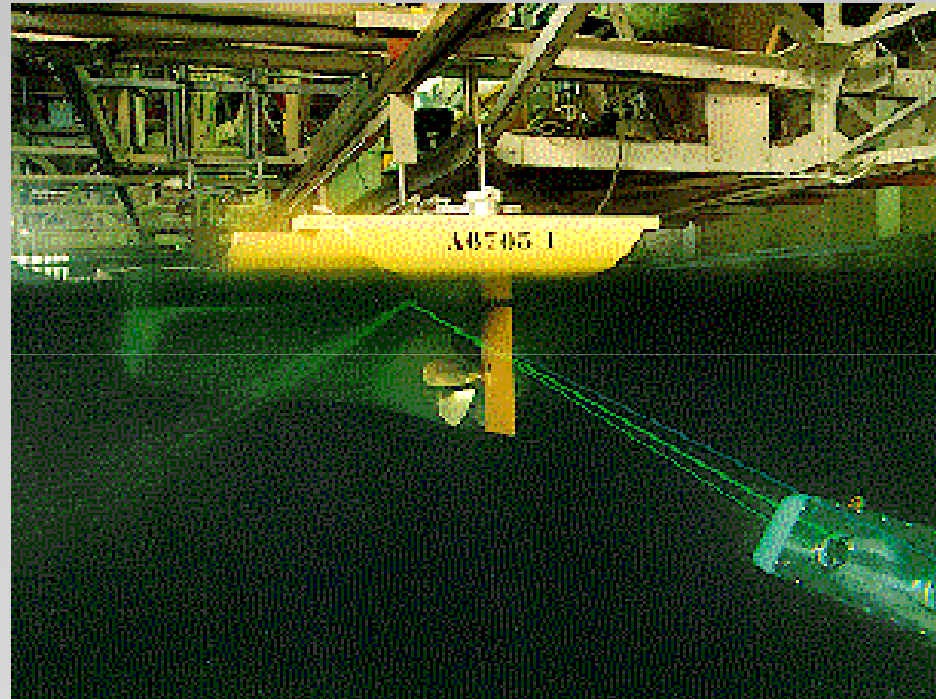


Photo courtesy of Marin, the Netherlands

Measurement of air flow field around a ship model in a wind tunnel

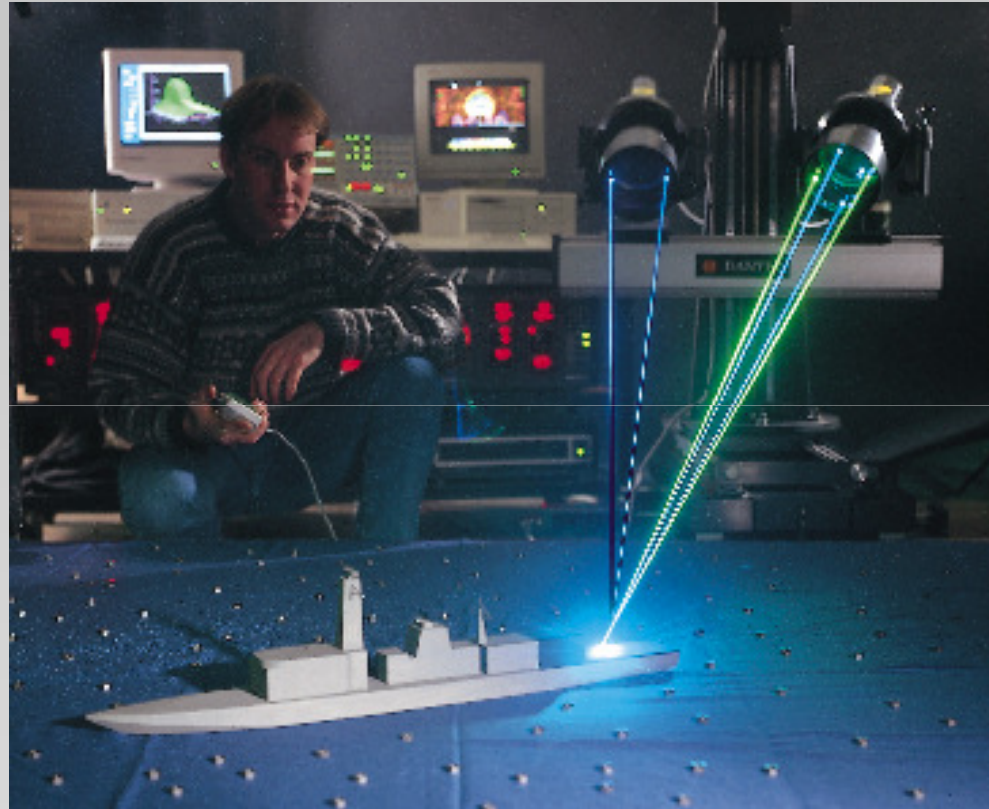
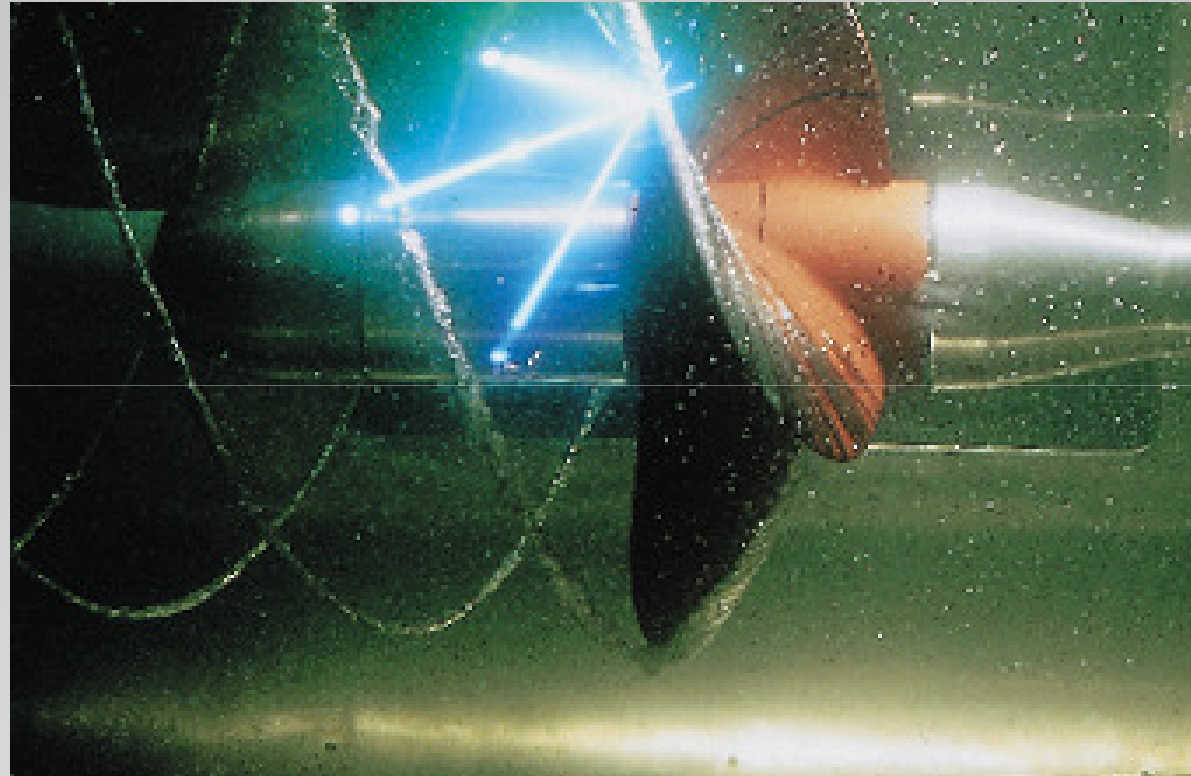
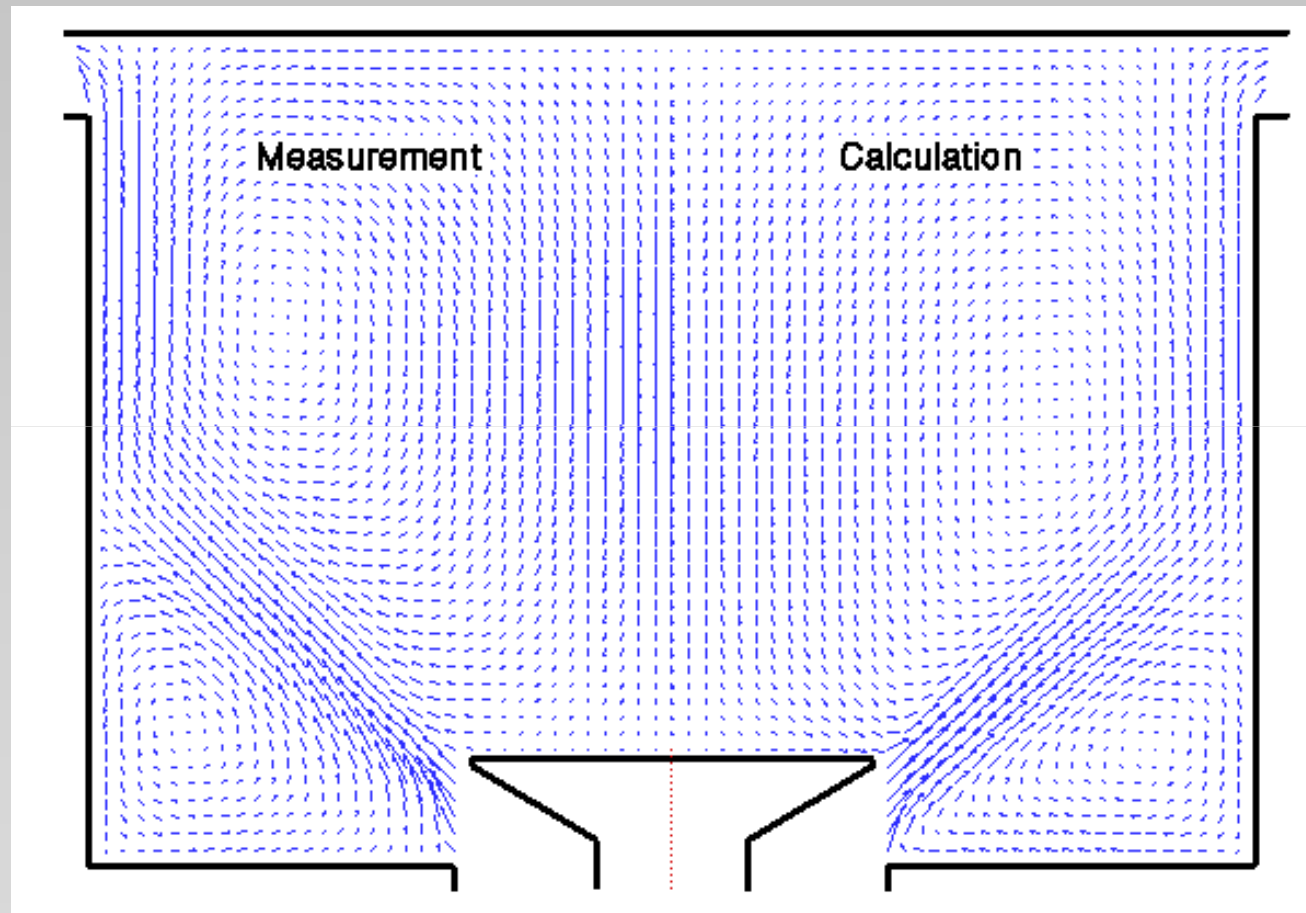


Photo courtesy of University of Bristol, UK

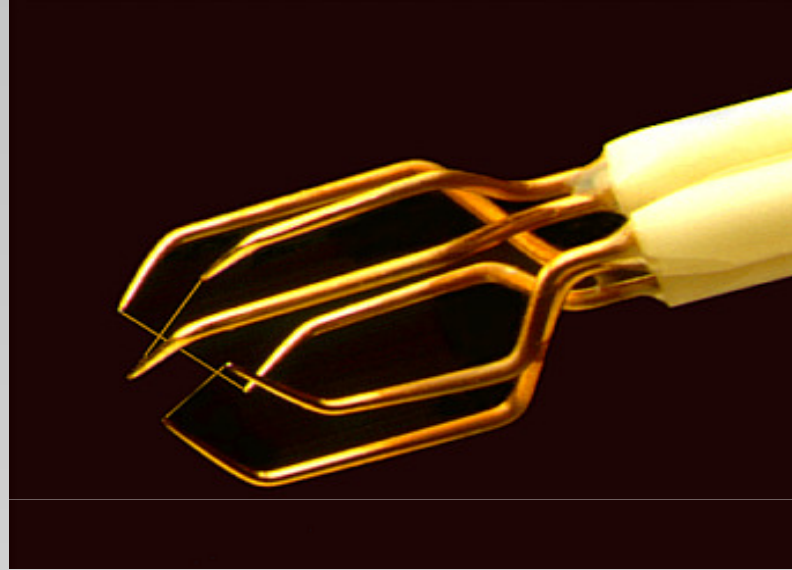
Measurement of flow around a ship propeller in a cavitation tank



Comparison of EFD and CFD results



Hot-Wire Anemometry



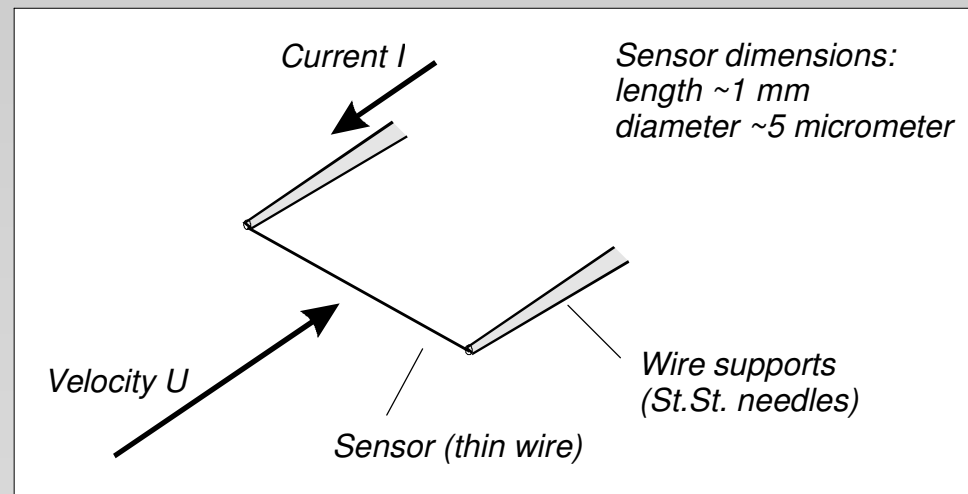
- **Purpose:**
to measure mean and fluctuating variables in fluid flows (velocity, temperature, etc.): mean velocity, turbulence characteristics – **TURBULENCE STUDIES; IMPROVEMENT OF TURBULENCE MODELS**

Principles of operation

- Consider a thin wire mounted to supports and exposed to a velocity U .

When a current is passed through wire, heat is generated ($I^2 R_w$). In equilibrium, this must be balanced by heat loss (primarily convective) to the surroundings.

- If velocity changes, convective heat transfer coefficient will change, wire temperature will change and eventually reach a new equilibrium.



Governing equation

- **Governing Equation:** $\frac{dE}{dt} = W - H$

E = thermal energy stored in wire

$$E = CwTw$$

Cw = heat capacity of wire

W = power generated by Joule heating

$$W = I^2 R_w$$

recall $R_w = R_w(T_w)$

H = heat transferred to surroundings

Simplified static analysis I

- For equilibrium conditions the heat storage is zero:

$$\frac{dE}{dt} = 0 \quad \therefore W = H$$

and the Joule heating W equals the convective heat transfer H

- Assumptions
 - Radiation losses small
 - Conduction to wire supports small
 - T_w uniform over length of sensor
 - Velocity impinges normally on wire, and is uniform over its entire length, and also small compared to sonic speed.
 - Fluid temperature and density constant

Simplified static analysis II

Static heat transfer:

$$W = H \Rightarrow I^2 R_w = hA(T_w - T_a) \Rightarrow I^2 R_w = Nu k_f / d A (T_w - T_a)$$

h = film coefficient of heat transfer

A = heat transfer area

d = wire diameter

k_f = heat conductivity of fluid

Nu = dimensionless heat transfer coefficient

Forced convection regime, i.e. $Re > Gr^{1/3}$ (0.02 in air) and $Re < 140 \Rightarrow$

$$Nu = A_1 + B_1 \cdot Re^n = A_2 + B_2 \cdot U^n$$

$$I^2 R_w^2 = E^2 = (T_w - T_a)(A + B \cdot U^n) \quad \text{“King’s law”}$$

The voltage drop is used as a measure of velocity \Rightarrow data acquisition, processing

A, B, n: BY CALIBRATION

Constant Temperature Anemometer CTA

- **Principle:**

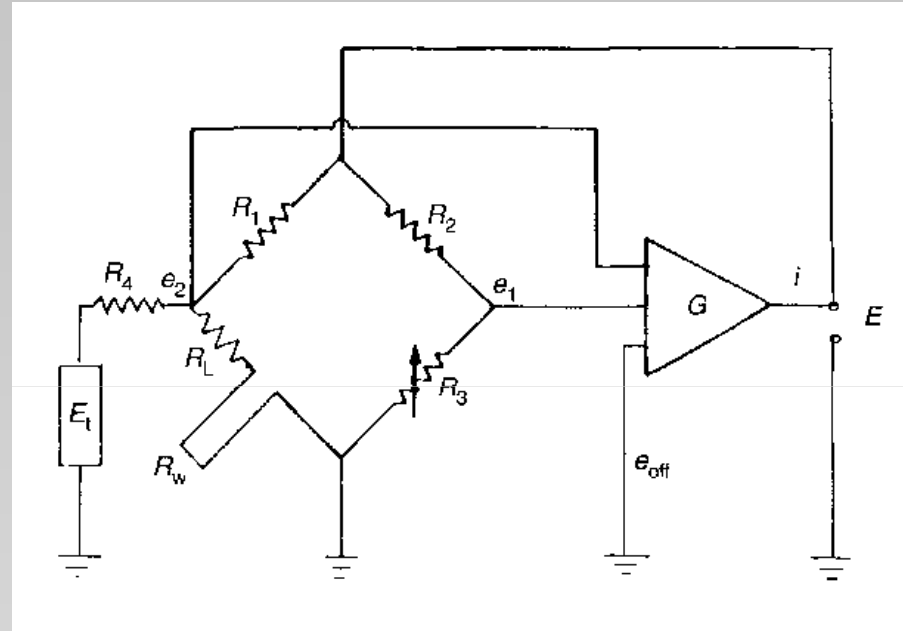
Sensor resistance is kept constant by servo amplifier

- **Advantages:**

- Easy to use
- High frequency response
- Low noise
- Accepted standard

- **Disadvantages:**

- More complex circuit



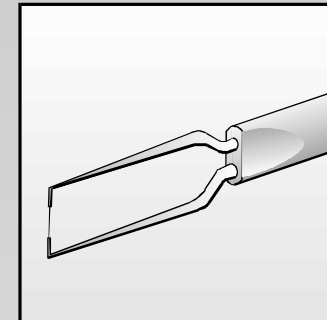
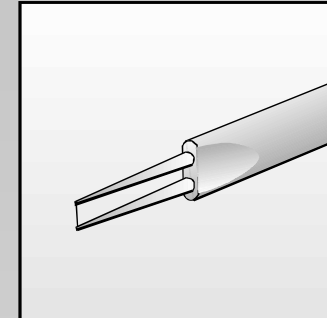
Probe types I

- **Miniature Wire Probes**
Platinum-plated tungsten,
5 μm diameter, 1.2 mm length

- **Gold-Plated Probes**
3 mm total wire length,
1.25 mm active sensor
copper ends, gold-plated

Advantages:

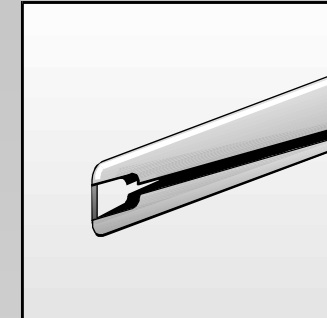
- accurately defined sensing length
- reduced heat dissipation by the prongs
- more uniform temperature distribution along wire
- less probe interference to the flow field



Probe types II

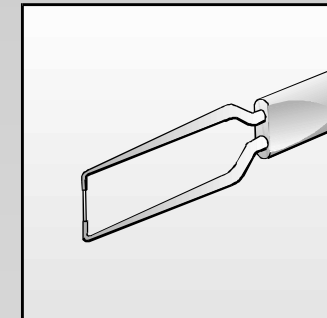
- **Film Probes**

Thin metal film (nickel) deposited on quartz body. Thin quartz layer protects metal film against corrosion, wear, physical damage, electrical action



- **Fiber-Film Probes**

“Hybrid” - film deposited on a thin wire-like quartz rod (fiber) “split fiber-film probes.”



Probe types III

- **X-probes for 2D flows**
2 sensors perpendicular to each other.
Measures within $\pm 45^\circ$.
- **Split-fiber probes for 2D flows**
2 film sensors opposite each other on a quartz cylinder. Measures within $\pm 90^\circ$.
- **Tri-axial probes for 3D flows**
3 sensors in an orthogonal system. Measures within 70° cone.

