Schemes

Variable speed drives

Altivar 12 Drives



Note: Install interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Compatible components (for a complete list of references, please refer to the "Motor starter solutions - Control and protection components" and "Motor starters up to 150 A" catalogues or visit "www.schneider-electric.com")				
Item no.	Description			
A1	ATV 120000F1 or ATV 120000M2 drive (see page 60402/2)			
A2	ATV 12000M3 drive (see page 60402/2)			
KM1	Contactor (only if a control circuit is needed; see page 60406/2)			
P1	2.2 k Ω reference potentiometer, SZ1 RV1202. This can be replaced by a 10 k Ω potentiometer (maximum).			
Q1	Circuit breaker (see page 60406/2)			

Examples of recommended schemes for logic and analog I/O 2-wire control 3-wire control Analog input configured Analog input configured for current for voltage ATV 120000 ATV 120000 ATV 1200000 ATV 1200000 **F24V** +24V SON ŝ A1 <u>b</u> E E F 2.2 kΩ...10 kΩ 0-20 mA reference 4-20 mA LI1: Stop LI2: Forward LIe: Reverse 10 \ LI1: Forward potentiometer supply LIe: Reverse External 10 V

Examples of recommended schemes for logic I/O powered by an external 24 V ---- supply (5) Connected as positive logic (Source) Connected as negative logic (Sink)





(1) The control section is connected in exactly the same way as for the ATV 12000F1 and ATV 12000M2 drives.

(2) Connection as positive logic (Source) or negative logic (Sink) is configured via parameters; the factory-set configuration is positive logic (Source).

(3) Fault relay contacts for remote signalling of the drive status.
(4) The R/L1, S/L2/N and T/L3 terminals are connected at the top of the drive. The other terminals are connected on the underside of the drive.

(5) Please refer to the "Phaseo power supplies and transformers" catalogue.

Presentation:	Characteristics:	References:	Dimensions:	Functions:
page 60400/2	page 60401/2	page 60402/2	page 60403/2	page 60407/2
2		Schneider Gelectric	version: 4.0	60404-EN.indd

Schemes (continued), installation recommendations

Recommended schemes (continued) Braking unit VW3 A7 005 used with braking

Variable speed drives

Altivar 12 Braking unit and resistors, motor chokes, additional EMC filters





Motor chokes VW3 A4 551...554

Additional EMC input filters VW3 A4 416...419







Connections for ensuring conformity to EMC standards

Principle

- Earths between the drive, motor and cable shielding must have "high frequency" equipotentiality.
- Use shielded cables with shielding connected to earth throughout 360° at both ends for the motor cable and the control-signalling cables. Conduit or metal ducting can be used for part of the shielding length provided that there is no break in the continuity of the earth connection.
- Ensure maximum separation between the line supply cable and the motor cable.

Installation diagram



Note: The HF equipotential earth connection between the drive, motor and cable shielding does not remove the need to connect the PE conductors (green-yellow) to the appropriate terminals on each unit. If using an additional EMC input filter, it should be mounted beneath the drive and connected directly to the line supply via an unshielded cable. Link 3 on the drive is then established via the filter output cable.

Use on an IT system (isolated or impedance earthed neutral)

Use a permanent insulation monitor, such as Schneider Electric's XM200, which is compatible with non-linear loads. ATV 12000 drives have integrated EMC filters.

For use on an IT system, these filters can easily be disconnected by means of a selector switch 10 which can be accessed without removing the drive.