

Turbulence I.

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Balogh

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Reynolds
equations

Turbulence modelling I. in Computational Fluid Dynamics

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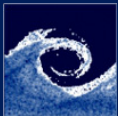


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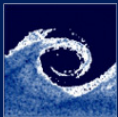
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History - Leonardo da Vinci, ca. 1500

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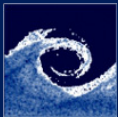
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Leonardo da Vinci (translation: Piomelli in Lumley, J.L., 1997):

"Observe the motion of the surface of the water, which resembles that of hair, which has two motions, of which one is caused by the weight of the hair, the other by the direction of the curls; thus the water has eddying motions, one part of which is due to the principal current, the other to random and reverse motion"





Art - Vincent van Gogh : Starry night, 1889

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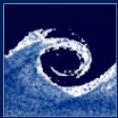
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Science - Reynolds experiment, 1883

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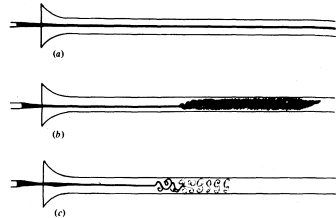
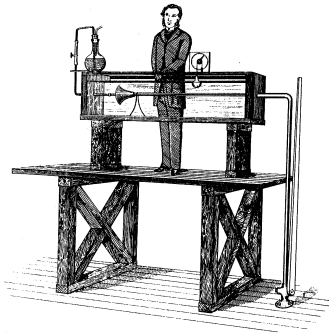
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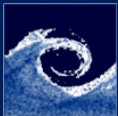
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Science - Quotations

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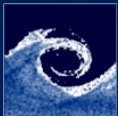
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Horace Lamb, 1932

“I am an old man now, and when I die and go to heaven there are two matters on which I hope for enlightenment. One is quantum electrodynamics, and the other is the turbulent motion of fluids. And about the former I am rather optimistic.”

Peter Bradshaw, 1994

“Turbulence was probably invented by the Devil on the seventh day of Creation when the Good Lord wasn't looking.”



Motivation

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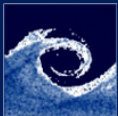
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Why to deal with turbulence in a CFD course?

- Most of the equations considered in **CFD are model** equations
- **Turbulence** is a phenomena which is present **in $\approx 95\%$ of CFD** applications
- **Turbulence** can only be very rarely simulated and usually **has to be modelled**
- **Basics** of turbulence are **required for the use** of the models



Our limitations, simplifications

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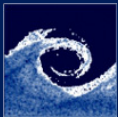
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Following effects are not considered:

- density variation ($\rho = const.$)
 - Shock wave and turbulence interaction excluded
 - Buoyancy effects on turbulence not treated
- viscosity variation ($\nu = const.$)
- effect of body forces ($g_i = 0$)
 - Except free surface flows, gravity has no effect, can be merged in the pressure



Definition

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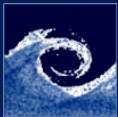
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Precise definition?

- No definition exists for turbulence till now
- Stability, chaos theory are the candidate disciplines to provide a definition
 - But the describing PDE's are much more complicated to treat than an ODE
- Last unsolved problem of classical physics ('Is it possible to make a theoretical model to describe the statistics of a turbulent flow?')
- Engineers still can deal with turbulence



Properties

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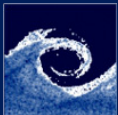
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Instead of a definition

- Properties of turbulent flows will be summarized
- These characteristics can be used to:
 - Distinguish between laminar (even unsteady) and turbulent flow
 - Find path toward the investigation of turbulence
 - Understanding the importance of turbulence in engineering problems



High Reynolds number

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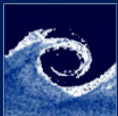
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Reynolds number

- $Re = \frac{UL}{\nu} = \frac{F_{inertial}}{F_{viscous}}$
- high Re number \longleftrightarrow viscous forces are small
- **But** inviscid flow is not turbulent

Role of Re

- Reynolds number is the bifurcation (stability) parameter of the flow
- $Re_{cr} \approx 2300$ for pipe flows
- $Re > Re_{cr} \Rightarrow$ flow becomes unstable, turbulent



Disordered, chaotic

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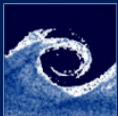
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- Terminology of dynamic systems
- Strong sensitivity on initial (IC) and boundary (BC) conditions
- Statement about the 'stability' of the flow
- PDE's (partial differential equations) have infinite times more degree of freedom (DoF) than ODE's (ordinary differential equations)
 - Much more difficult to be treated
 - Can be the candidate to give a definition of turbulence
- The tool to explain difference between turbulence and 'simple' laminar unsteadiness



Continuous spatial spectrum

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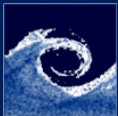
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Spatial spectrum

- Spatial spectrum is analogous to temporal, used to defined via Fourier transformation
- Practically, periodic or infinite long domain is more difficult to find
- Visually: Flow features of every size are present (between the bounds of common sense)

Counter-example

Acoustic waves have spiked spectrum, with sub and super harmonics.



3D phenomena

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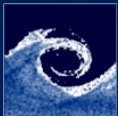
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- **Vortex stretching** (see e.g. Advanced Fluid Dynamics) is only present in 3D flows.
- In 2D there is no velocity component in the direction of the vorticity to stretch vortices.
- Stretching is responsible for **scale reduction**,
- and **vorticity enhancement**.

Averaged flow can be 2D

- An unsteady flowfield **must be 3D**
- The (Reynolds or time) averaged flowfield can be 2D
 - Spanwise fluctuations are averaged to zero, but they are playing role in the creation of streamwise, and wall normal fluctuations.



Unsteady

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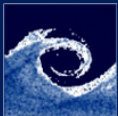
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Turbulent flow is unsteady, but unsteadiness **does not mean turbulence**

Stability of unsteady flow can be different

- In an unsteady laminar pipe flow (e.g. $500 < Re_b(t) < 1000$), the dependency on small perturbations is smooth and continuous
- In an unsteady turbulent pipe flow (e.g. $5000 < Re_b(t) < 5500$), the dependency on small perturbations is strong



Continuum phenomena

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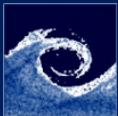
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- Can be described by the continuum Navier-Stokes (NS) equations
- I.e. **molecular phenomena is not involved** as it was thought 100 years ago

Conclusions

- ① **Can be simulated by solving the NS equations** (Direct Numerical Simulation = **DNS**)
- ② A smallest existing length scales of turbulence are remarkably bigger than the molecular scales
- ③ There are cases, where molecular effects are important (re-entry capsule → Boltzmann eq.)
- ④ Turbulence is not fed by molecular resonations, but it is a property (stability type) of the solution of the NS



Dissipative

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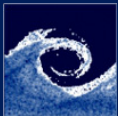
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Dissipative

- Def: Conversion of mechanical (kinetic energy) to heat (raise the temperature)
- Always present in turbulent flows
- It happens at small scales of turbulence, where viscous forces are important compared to inertia
- It is a remarkable difference compared to wave motion, where dissipation is not of primary importance



Vortical

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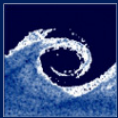
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Turbulent flows are always vortical

- Since vortex stretching is responsible for scale reduction
- Towards dissipation, which is only active at the smallest scales



Diffusive

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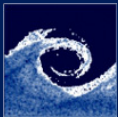
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Diffusive property, the engineering consequence

- By means of averaged turbulent quantities, transfer intensities are increased
 - E.g. transfer coefficients are increased (e.g. λ)
 - Nusselt number is increased
- By means of averaged turbulent fields, transfer coefficients are increased
 - Turbulent viscosity (momentum transfer) is increased
 - Turbulent heat conduction coefficient is increased
 - Turbulent diffusion coefficients are increased



Has history, flow dependent, THE TURBULENCE does not exist

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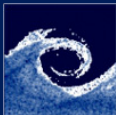
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As formulated in the *last unsolved problem of classical physics* **no general rule** of the turbulence could be developed till now.

No universal theory of turbulence has been discovered

- Turbulent flows can be of different type, e.g.:
 - They can be boundary condition dependent (constraints)
 - They depend on upstream conditions (spatial history)
 - They depend on temporal history



Summarized properties

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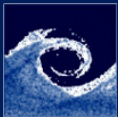
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- High Reynolds number
- Disordered, chaotic
- Continuous spatial spectrum
- Spatial and temporal phenomena (4D)
- Continuum phenomena (not molecular)
- Vortical
- Dissipative, Diffusive
- Has history (spatial and temporal)



Notations

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Directions

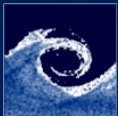
- x, u : Streamwise direction
- y, v : Wall normal direction, points to the highest gradient
- z, w : Bi normal to x, y , spanwise direction

Index notation

$$x = x_1, y = x_2, z = x_3 \quad u = u_1, v = u_2, w = u_3$$

Partial derivatives

$$\partial_j \stackrel{\text{def}}{=} \frac{\partial}{\partial x_j} \quad \partial_t \stackrel{\text{def}}{=} \frac{\partial}{\partial t}$$



Summation convention

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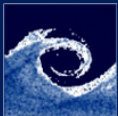
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Summation is carried out for double indices for the three spatial directions.

Very basic example

Scalar product:

$$a_i b_i \stackrel{\text{def}}{=} \sum_{i=1}^3 a_i b_i \quad (1)$$



NS as example

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Continuity eq. in vectorial form and with short notation

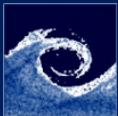
$$\frac{\partial \rho}{\partial t} + \operatorname{div}(\rho \mathbf{v}) = 0 \quad (2)$$

$$\partial_t \rho + \partial_i u_i = 0 \quad (3)$$

Momentum eq. in vectorial form and with short notation

$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = \mathbf{g} - \frac{1}{\rho} \nabla p + \nu \left[\nabla^2 \mathbf{u} + \frac{1}{3} \nabla (\nabla \cdot \mathbf{u}) \right] \quad (4)$$

$$\partial_t u_i + u_j \partial_j u_i = g_i - \frac{1}{\rho} \partial_i p + \nu \left[\partial_j \partial_j u_i + \frac{1}{3} \partial_i (\partial_j u_j) \right] \quad (5)$$



Statistical description

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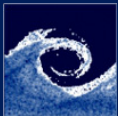
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The 'simple' approach

Turbulent flow can be characterised by its **time average** and the **fluctuation** compared to it

Problems of this approach

- How long should be the time average?
- How to distinguish between unsteadiness and turbulence?



Statistical description

Examples

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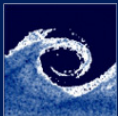
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Flow examples

- Turbulent pipe flow having ($Re \gg 2300$), driven by a piston pump (sinusoidal unsteadiness)
- Von Kármán vortex street around a cylinder of $Re = 10^5$, where the vortices are shedding with the frequency of $St = 0.2$

Difficult to distinguish between turbulence and unsteadiness



Ensemble average

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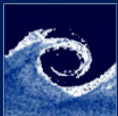
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Why to treat deterministic process by statistics?

- NS equations are deterministic (at least we believe, not proven generally)
- I.e. the solution is determined by IC's and BC's
- Statistical description is useful because of the chaotic behaviour
 - The high sensitivity to the BC's and IC's
 - Possible to treat statistically the result with similar (but not identical) set of BC's and IC's



Ensemble prediction (perturbed IC's)

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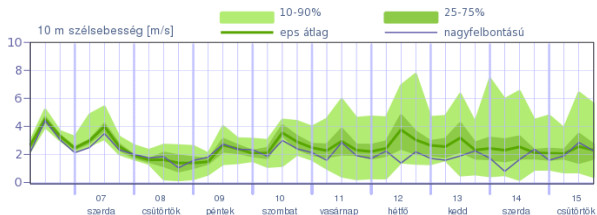
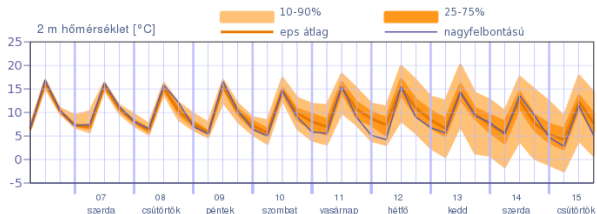
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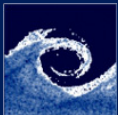
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ECMWF valószínűségi előrejelzés: Budapest

Készült: 2018.11.06 00 UTC-s futtatásból





Solution as a statistical variable

$$\varphi = \varphi(x, y, z, t, i) \quad (6)$$

Index i corresponds to similar but not identical BC's and IC's

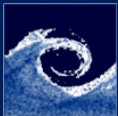
Density function

- Shows the 'probability' of a value of φ .

$$f(\varphi) \quad (7)$$

- It is normed:

$$\int_{-\infty}^{\infty} f(\varphi) d\varphi = 1 \quad (8)$$



Mean value

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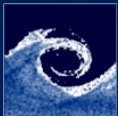
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Expected value

$$\overline{\varphi(x, y, z, t)} = \int_{-\infty}^{\infty} \varphi(x, y, z, t) f(\varphi(x, y, z, t)) d\varphi \quad (9)$$

Average

$$\overline{\varphi(x, y, z, t)} = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N \varphi(x, y, z, t, i) \quad (10)$$



Reynolds averaging

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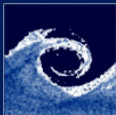
Reynolds decomposition

Since the ensemble averaging is called Reynolds averaging, the decomposition is named also after Reynolds

$$\varphi = \bar{\varphi} + \varphi' \quad (11)$$

Fluctuation

$$\varphi' \stackrel{\text{def}}{=} \varphi - \bar{\varphi} \quad (12)$$



Properties of the averaging

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Linearity

$$\overline{a\varphi + b\psi} = a\overline{\varphi} + b\overline{\psi} \quad (13)$$

The Reynolds averaging acts only once

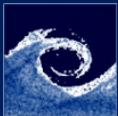
$$\overline{\overline{\varphi}} = \overline{\varphi} \quad (14)$$

Average of fluctuations is zero

$$\overline{\varphi'} = 0 \quad (15)$$

Commutative to derivation

$$\overline{\partial\varphi} = \partial\overline{\varphi}$$



Deviation

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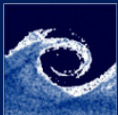
Deviation

- First characteristics of the fluctuations

-

$$\sigma_{\varphi} = \sqrt{\overline{\varphi'^2}} \quad (16)$$

- Also called as RMS: $\varphi_{rms} \stackrel{\text{def}}{=} \sigma_{\varphi}$



Connection between time and ensemble average

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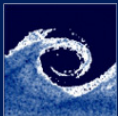
Ergodicity

Time and ensemble averages are equal. I.e. the statistics are independent from the initial condition.

Average is the same, deviation... ?

$$\hat{\varphi}^{(T)} = \frac{1}{T} \int_0^T \varphi \, dt \quad (17)$$

$$\overline{\hat{\varphi}^{(T)}} = \frac{1}{T} \int_0^T \bar{\varphi} \, dt = \bar{\varphi} \quad (18)$$



Covariance

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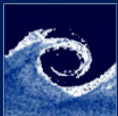
Covariance

$$\begin{aligned} R_{\varphi\psi} &= R_{\varphi\psi}(x, y, z, t, \delta x, \delta y, \delta z, \tau) = \\ &= \overline{\varphi'(x, y, z, t)\psi'(x + \delta x, y + \delta y, z + \delta z, t + \tau)} \end{aligned}$$

Auto covariance

- If $\varphi = \psi$ covariance is called auto-covariance
- E.g. Time auto covariance:

$$R_{\varphi\varphi}(x, y, z, t, 0, 0, 0, \tau) \quad (19)$$



Correlation

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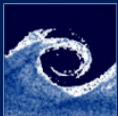
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Correlation

Non-dimensional covariance

$$\rho_{\varphi\psi}(x, y, z, t, \delta x, \delta y, \delta z, \tau) = \frac{R_{\varphi\psi}}{\sigma_{\varphi(x,y,z,t)}\sigma_{\psi(x+\delta x, y+\delta y, z+\delta z, t+\tau)}} \quad (20)$$



Integral time scale

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Definition

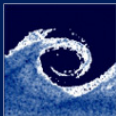
Notations

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Integral time scale

$$T_{\varphi\psi}(x, y, z, t) = \int_{-\infty}^{+\infty} \rho_{\varphi\psi}(x, y, z, t, 0, 0, 0, \tau) \, d\tau \quad (21)$$



Taylor frozen vortex hypothesis

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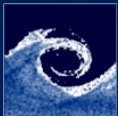
It is much more easy to measure the integral time scale (hot-wire) than the length scale (two hot-wires at variable distance)

Assumptions

- The flow field is completely frozen, characterised by the mean flow (U)
- The streamwise length scale can be approximated, by considering the temporal evolution of the frozen flowfield

Taylor approximated streamwise length scale

$$L_x = TU \quad (22)$$



Reynolds equations

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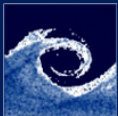
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The **Reynolds averaged NS equations** (RANS) will be developed. The RANS equations are also called as **Reynolds equations**.

Recipe

- Averaging the equations,
- where the variables are substituted by their Reynolds decomposed form



Reynolds Averaged Continuity

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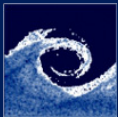
The original equation

$$\partial_i u_i = 0$$

Development:

$$\begin{aligned}\overline{\partial_i u_i} &= \\ &= \partial_i \overline{u_i} \\ &= \partial_i \overline{u_i + u'_i} \\ &= \partial_i \overline{u_i} \\ &= \partial_i \overline{u_i} = 0\end{aligned}\tag{23}$$

Same equation but for the average!



Momentum equations

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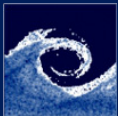
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Derivation

- Same rules applied to the linear term (no difference only)
- Non-linear term is different



Averaging of the non-linear term (convective acceleration)

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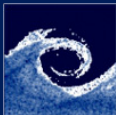
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$$\begin{aligned}\overline{u_j \partial_j u_i} &= \\ &= \overline{\partial_j (u_j u_i)} \\ &= \partial_j \overline{u_j u_i} \\ &= \partial_j (\overline{u_j} + u'_j) (\overline{u_i} + u'_i) \\ &= \partial_j (\overline{u_j u_i} + \overline{u_i u'_j} + \overline{u_j u'_i} + \overline{u'_j u'_i}) \\ &= \partial_j (\overline{u_j u_i} + \overline{u'_j u'_i}) \\ &= \partial_j (\overline{u_j u_i}) + \partial_j \overline{u'_j u'_i} \\ &= \overline{u_j} \partial_j \overline{u_i} + \partial_j \overline{u'_i u'_j}\end{aligned}\tag{24}$$



Reynolds equations

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Continuity equation

$$\partial_i \bar{u}_i = 0$$

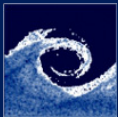
Momentum equation

$$\partial_t \bar{u}_i + \bar{u}_j \partial_j \bar{u}_i = -\frac{1}{\rho} \partial_i \bar{p} + \nu \partial_j \partial_j \bar{u}_i - \partial_j \overline{u'_i u'_j} \quad (25)$$

Reynold stress tensor

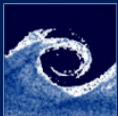
$$\overline{u'_i u'_j} \quad (26)$$

Or multiplied by ρ , or -1 times



All stresses causing the acceleration

$$\tau_{ij} = -\frac{1}{\rho} \bar{p} \delta_{ij} + \nu \partial_j \bar{u}_i - \overline{u'_i u'_j} \quad (27)$$



Questions?

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Thanks for your attention!